

Design Wien Bridge Oscillator for VLF to VHF Using Practical Op – Amp

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ABSTRACT- An electronic oscillator is generally a major part of electrical, electronic and communications circuits and systems and it can be divided into linear and nonlinear families. Wien Bridge is a type of RC phase shift oscillators mostly used for around 1MHz and its design adopts positive feedback technology. In this research, novel look the reasons for the inability to achieve high frequencies was understanding and the ambiguity was removing from the determinants of obtaining a high frequency signal for this type of oscillators, also, new results were obtained with a unique presentation. The output formula for the oscillation resonant frequency was deriving based on the oscillator's theory. The design has been successfully achieved by using a practical high-performance op-amp and from the simulation results the frequency bandwidth was 50.7211 MHz from VLF (9.83 HZ) to VHF (50.73 MHz) and. These unique and interesting scientific findings were encouraging.

Keywords: RC, Wien Bridge Oscillator, LF-MF-VHF, OP-AMP.

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1. INTRODUCTION

It is one of basic types of oscillators, which produce sinusoidal signal. Max Wien was accomplishing its basic idea as four arms electrical balance bridge in 1891 for calculating and gauging impedances [1]. It is construct from one operational amplifier and two groups of resistors and capacitors in a way that looks like both types of feedback (FB), -ve FB used to get voltage amplification and keep its constant level and the +ve FB is connected through RC passive BPF to get desired output oscillation resonance frequency [2-5]. In general, RC phase shift oscillator is used to generate signals typically used for frequencies nearly or equal to about 1 MHz as traditional Wien bridge oscillator. In comparison of 30 years ago [6-9] and recent years with the advent of new high performance of operational amplifier, manufacturers of operational amplifier made it suitable for high frequency applications. This new technology, with modern high-speed op-amp led to introduce high frequency generators based on Wien bridge oscillation theory. These oscillators have better characteristic such as an improved

bandwidth and stability, controlling input and output impedance, decreasing noise and distortion.

The problematic statement in the Wien bridge oscillator design is that in the Wien Bridge oscillator design is that mostly a lot of text books such as [10-20], also many present journals such as [21-26] state that there is limits of resonance frequency of output signal of Wien bridge oscillator is that these frequency not exceed one megahertz. These and many other references do not clearly mention what these limitations are and how it is can be resolved theoretically or practically.

Successful solutions to the above-mentioned problem were giving in the following sections of this paper.

Which state that the advent of high performance Op-amp & using it as forward open loop for different positive feedback configuration circuit has make the new generation of Wien bridge oscillator, are capable to introduce output signal with high performance characteristic for very low to very high frequency.

2. METHODOLOGY AND MATHEMATICAL MODEL

In this, a Wien bridge oscillator is designing, firstly using theoretical information technology as shown in figure 1. It includes a high-performance operational amplifier and an RC positive feedback circuit in the closed loop as shown in figure 2. In this work, the used op-amp is non-inverting. In order to get a Phase difference of zero degree and a forward gain mostly a little more than one to satisfy Barkhausen's condition. for the initiation of oscillations in the circuit [27-29]. Secondly, the

above design was implemented using simulation software (Multisim12).

After applying the electrical circuit theories to the proposed design circuit shown in figure 1, Z_p and Z_s were calculating as in equations 1, 2 respectively

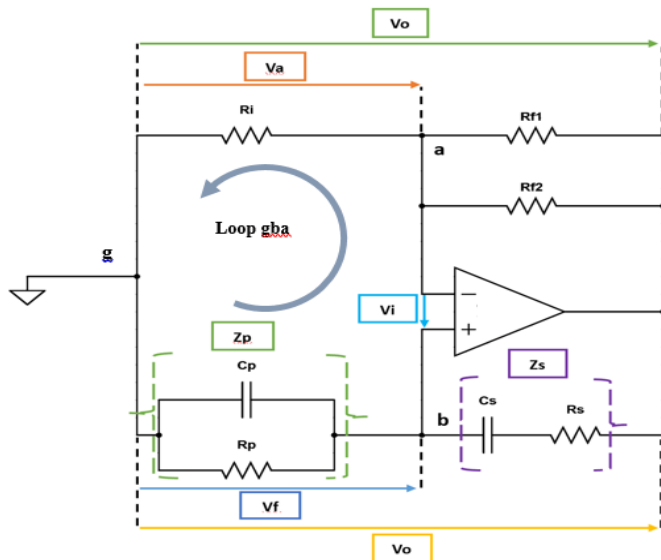


Figure 1. Suggested circuit design scheme

$$Z_p = \frac{R_p}{1 + j\omega C_p R_p} \quad (1)$$

$$Z_s = R_s + \frac{1}{j\omega C_s} \quad (2)$$

$$V_f = \frac{V_o}{Z_s + Z_p} * Z_p \quad (3)$$

$$V_a = \frac{V_o}{R_f + R_i} * R_i \quad (4)$$

By applying KVL on the closed loop gba of circuit, diagram of figure1

$$V_f - V_i - V_a = 0 \quad (5)$$

Depending on the c/s of ideal op-amp and oscillation theory. The voltage V_i can be taken a zero value so that;

$$V_f - V_a = 0$$

Substitute the values of V_f & V_a from equations (3) & (4) into equation (5) getting that:

$$\frac{R_s}{(R_s + R_p) + \frac{C_p R_p}{j\omega} + j(\omega C_p R_s R_p - \frac{1}{\omega C_s})} = \frac{R_i}{R_f + R_i} \quad (6)$$

From these above equations of the proposal design, the circuit works at oscillation frequency satisfies the Barkhausen condition, which state that $|AB|=1$, and $\angle AB=0$. (Unity loop & zero phase shift degree) [28-34]. To derive the maximum output frequency signal which is called resonant frequency that happen at resonance the imaginary part of equation (6) above equal to zero, therefore:

$$\omega C_p R_s R_p = \frac{1}{\omega C_s}, \quad \omega^2 = \frac{1}{R_s R_p C_s C_p}, \quad f_r = \frac{1}{2\pi \sqrt{R_s R_p C_s C_p}} \quad (7)$$

Also, equation (6) after taken imaginary part at zero & $R_s=R_p=R$ & $C_s=C_p=C$, equation (6) become as follows

$$\frac{R_p}{R_s + R_p + \frac{C_p R_s}{C_s}} = \frac{R_i}{R_f + R_i}$$

$$\frac{R}{R + R + R} = \frac{R_i}{R_f + R_i}$$

$$\frac{1}{3} = \frac{R_i}{R_f + R_i}$$

$$R_f = R_f1 // R_f2 = 2R_i$$

3. BARKHAUSEN MODIFIED CRITERIA & MAXIMUM FREQUENCY LIMITATION INVESTIGATIONS

The modification of the Barkhausen conditions for oscillators was used to securing the oscillation of the oscillators when the linear oscillator circuit becomes unstable. Due to shift the position of poles to the right side of the frequency plane. In order for the oscillations to start, continuing and stability, these poles must be on conjugate complex pair form and on the imaginary axis of the frequency plane. Hence, we can understand the FB circuit as a prerequisite for the occurrence of oscillations. It is a new look at the role of this property in the presence of existing oscillations so this modification is called the modified Barkhausen criterion. [35-43] Factors determining the ability to achieve high resonant frequencies of the oscillator signal were investigated. These factors that are identified, understood, and studied are unit gain bandwidth (f_T), turn rate (slew rate SR), and output voltage of the device ($V_o = V_{in} A_v$) as shown in equations 8, 9, 10, 11. [42-46] Thus, the ambiguity has been removed from the parameters of obtaining a high frequency signal for this type of oscillator.

Where the upper limits of its resonant frequency was restricted with the elements, product of gain bandwidth (f_T), slew rate which did help determine the maximum input frequency and amplitude of the output signal from the oscillator so that the output is not distorted too much, also voltage gain (A_v) & peak voltage (V_m) of sinusoidal output voltage as following.

$$V_o(t) = V_m \sin \omega t \quad (8)$$

$$SR = (dV_o(t))/dt = (d(V_m \sin \omega t))/dt = V_m \cdot \omega \cdot \cos \omega t \quad (9)$$

$$SR = 2\pi f_m \cdot V_m \quad (10)$$

$$f_{mo} = (SR)/(2\pi V_m) \quad (11)$$

Where:

f_{mo} : Maximum frequency of oscillation; SR: Slew rate of op amp; and $|V_m|$: Absolute peak value of output voltage (V_o).

Thus, it becomes necessary to check the data sheet for of the device before using it for high frequency applications. The type of op amp is LM171AIN was used in this design.

The two parallel diodes D1 and D2 in the above design serves as an excellent circuit for regulating the control required of the output of op amp voltage. This is in order to keep the BJTs operating point of Op-amp working in an active region away from saturation and lower cutoff regions so that D1 & D2 is considered as an automatic control of the output voltage. As mentioned above, the value of the maximum frequency fluctuation (f_{mo}) for this proposed design is approximately equal to or slightly smaller than the value indicated in equation (11).

4. SIMULATION RESULTS

Figure 2 shows the sub final circuit of the simulated design for VLF to VHF output signals. This circuit of the design was implemented using software Multisim program, which is a powerful electronic simulation program mostly used to design, implement and simulate electronic circuits and systems. The frequency values required to be obtained for the signal generated in the designed circuit depend on choosing the values of capacitances and resistors (R_s , R_p , C_s & C_p) as shown in equation (7).

Mathematical calculations such as bandwidth was 249.99999 Mhz of VLF (10hz) to VHF (250Mhz) obtained from the application of this equation, and figures 1, 2, and 3.

The simulation results of the measured frequency bandwidth was 50.7211 MHZ from, VLF (9.83 HZ) to VHF (50.73 MHZ) and other important parameters with related figure 4(A)-4(L) were presented in table 1. Where the above equation depends on the following elements R_s , R_p , C_s , & C_p . After relying on statistical theories in the principle of right and wrong, and verifying the results of the frequencies in the above equation in terms of signal stability. According to stability considerations and linear stability, the results are better if the values of (R_s & R_p) are reduced to the least possible without prejudice to conditions stability. Therefore, $R_s = R_p = 520 \Omega$ was chosen, and accordingly equation 10 was deduced from equation 7 after substitution R_s & R_p with its above chosen values.

$$f_r = \frac{0.1923}{200\pi\sqrt{C_s C_p}} \quad (12)$$

Table (1) shows calculations parameters values & signals measurements and the time taken to start oscillation of the final simulation scheme circuit shown in figure 3.

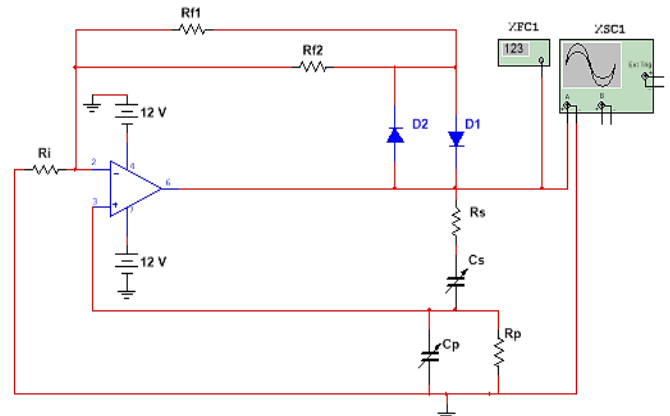


Figure 2. sub final circuit of the design

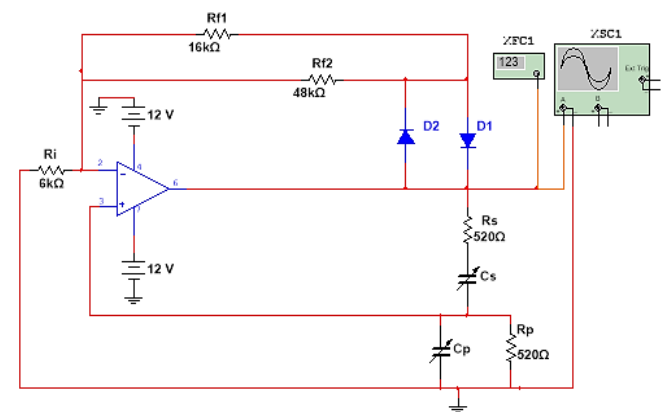
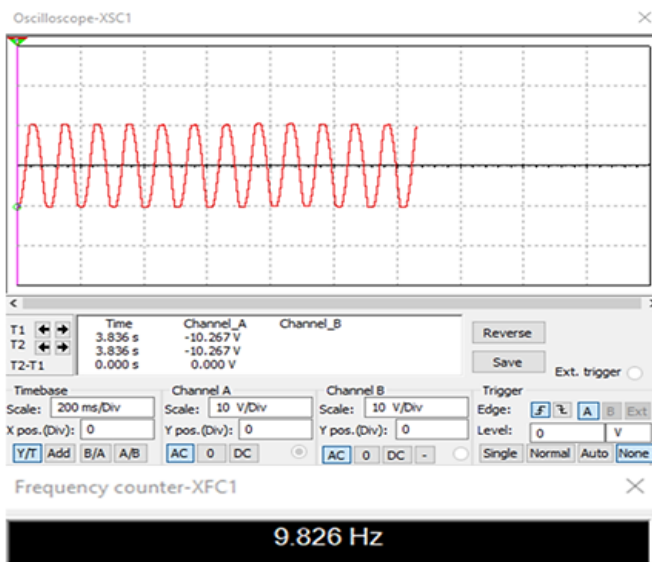


Figure 3. Final simulation scheme circuit

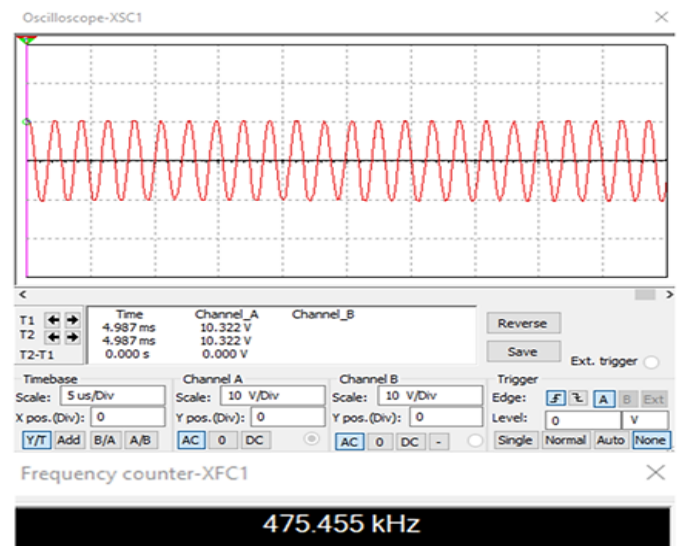
Table 1: Calculations parameters values & signals measurements

Feedback Parameters		Resonance Frequency (f_r)		Time Taken to Start Oscillation	Proposal Circuit with Output Signal Shape
$R_s = R_p$	$C_s = C_p$	Theoretically Calculation	Measurement Simulation		
520 Ω	159.155 μF	10 Hz	9.826 Hz	30 second	Figure 4-A
520 Ω	3.0606 μF	100 Hz	98.263 Hz	4.5 second	-
520 Ω	612.1 nF	500 Hz	491.255 Hz	< 2 second	-
520 Ω	306.606 nF	1000 Hz	982.203 Hz	< 1 second	-
520 Ω	30.606 nF	10 KHz	9.603 KHz	< 1 second	Figure 4-B
520 Ω	3.0606 pF	100 KHz	93.564 KHz	1 second	-
520 Ω	0.6 pF	500 KHz	475.455 KHz	3 second	Figure 4-C
520 Ω	382.58 pF	800 KHz	750 KHz	8 second	-
520 Ω	306 pF	1.0 MHz	955 KHz	20 second	Figure 4-D
520 Ω	218.62 pF	1.4 MHz	1.351 MHz	1 minute & 40 sec	-
520 Ω	102.02 pF	3.0 MHz	3.02 MHz	22 minute & 38 sec	-

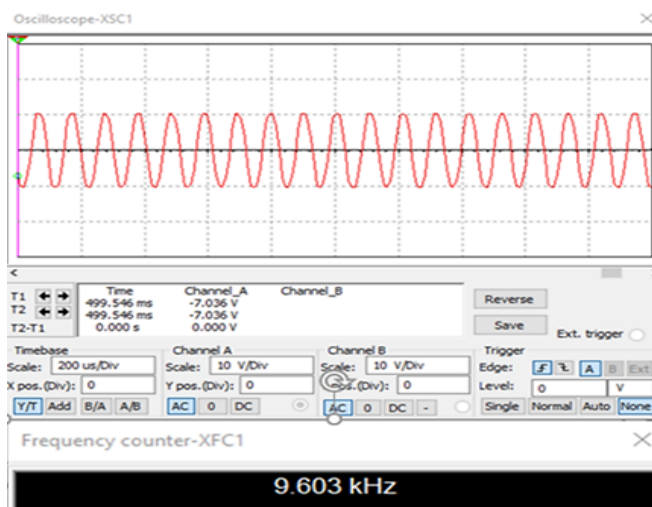
520 Ω	61.21 pF	5.0 MHz	5.225 MHz	30 minutes	Figure 4-E
520 Ω	43.73 pF	7.0 MHz	7.494 MHz	29 minutes	-
520 Ω	30.08 pF	10.0 MHz	10.837 MHz	16 minutes	-
520 Ω	20.4 pF	15.0 MHz	15.148 MHz	12.5 minute	Figure 4-F
520 Ω	15.3 pF	20.0 MHz	18.915 MHz	12 minutes	-
520 Ω	12.24 pF	25.0 MHz	21.527 MHz	11 minutes	-
520 Ω	10.2 pF	30.0 MHz	23.986 MHz	13 minutes	Figure 4-G
520 Ω	7.65 pF	40.0 MHz	27.847 MHz	12 minutes	
520 Ω	5.1 pF	60.0 MHz	33.344 MHz	15.18 minute	Figure 4-H
520 Ω	3.06 pF	100.0 MHz	40.194 MHz	30 minutes	-
520 Ω	2.509 pF	122.0 MHz	42.869 MHz	37 minutes	-
520 Ω	2 pF	153.0 MHz	45.651 MHz	35 minutes	Figure 4-I
520 Ω	1.913 pF	160 MHz	46.282 MHz	39 minutes	Figure 4-J
520 Ω	1.7 pF	180 MHz	47.648 MHz	43 minutes	-
520 Ω	1.531 pF	200 MHz	48.764 MHz	53 minute & 30sec	Figure 4-K
520 Ω	1.22488 pF	250 MHz	50.73 MHz	75minute& 30 sec	Figure 4-L



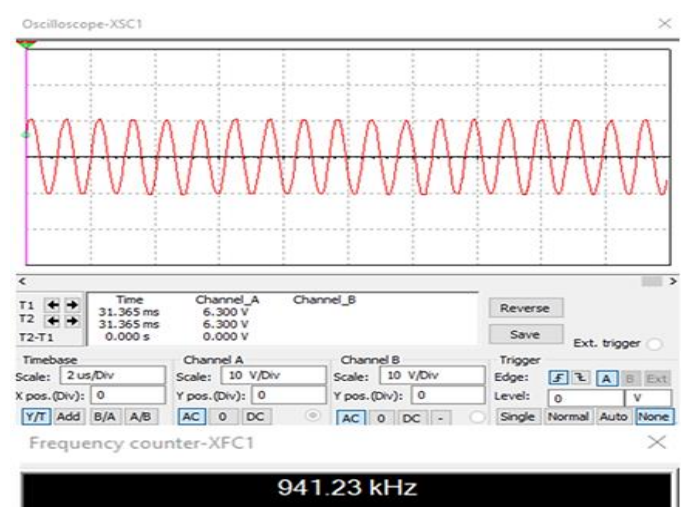
(a) Foc = 10 Hz



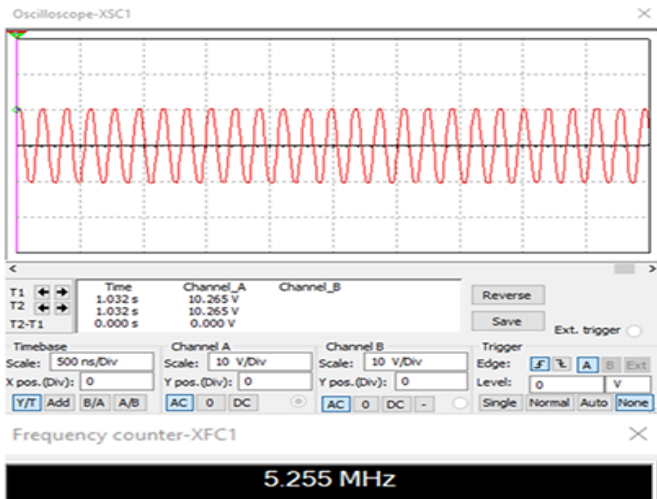
(c) Foc = 500 KHz



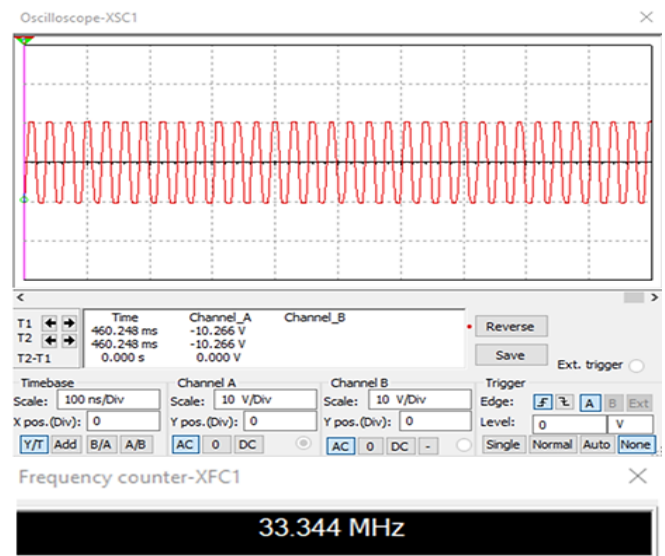
(b) Foc = 10 KHz



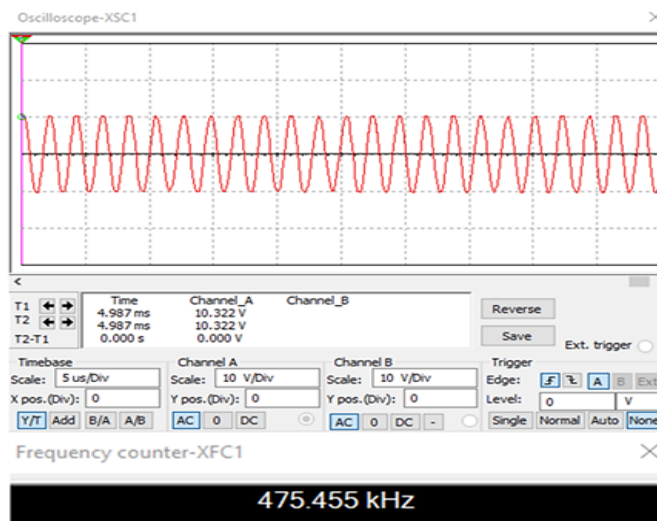
(d) Foc = 1 MHz



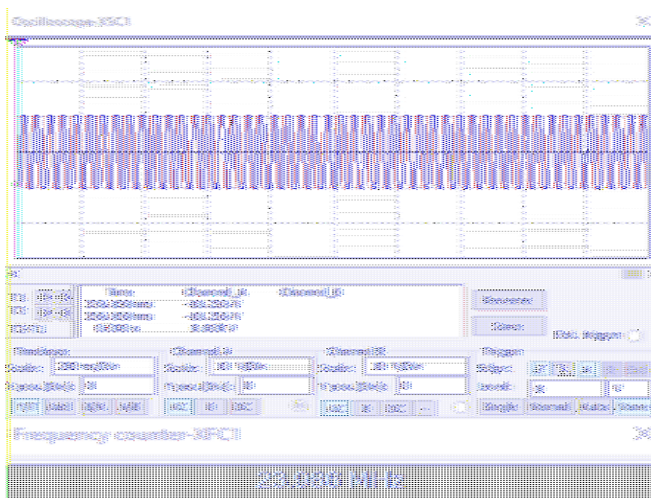
(e) Foc = 5 MHz



(h) Foc = 60 MHz



(f) Foc = 15 MHz



(g) Foc = 30 MHz

5. CONCLUSION

The schematic diagram of designed circuit is comprised from operational amplifier has absolute gain equal three. This operation amplifier has a unique c/s, such as high slew rate and very large input impedance accordingly, it became possible to be more appropriate and more effective in building and designing systems with high characteristics and performance when they are part of signal generation systems and circuits, including oscillators.

The measurement signals generated by the designed circuit disappear when the gain of the loop (AB) is less than one, and this signal is unstable when the gain of the loop (AB) is greater than one.

While the signal has a constant amplitude and a constant frequency when $|AB|=1.X$ ($X=0.001, 0.002$ to 0.009) and according to values of capacitances and resistances (R_s , R_p , C_s and C_p) that are chosen and compensated for the purpose of finding the resonant frequency as in *equation (7)*. This is can only be achieved after Barkhausen's oscillation condition is satisfied. Among the results recorded in Table -1- regarding the values of the measured signal frequencies for the designed circuit. By comparing these measured signal frequencies with the theoretically calculated frequencies according to *equation (7)* for the same values of the designed circuit elements. After observing the values of these frequencies, as we mentioned above, there are some differences between the values of high frequencies above 40 MHz of the measured signal and those calculated theoretically as shown in *table 1*.

Based on the presentation and interpretation in this research and through the analysis of these results (based on *equation 11* and *table 1*), it becomes clear that the main reason for these differences has become clear, which is the amount of R_S (slew rate) as well as the output voltage V_m , according to *equation (11)*.

It turns out that RS has the most prominent role in determining the maximum output frequency (fmo) resulting from the design according to *equation (11)*. Given the successive and tremendous development in the industry of high-performance integrated circuits, it will soon be easy to obtain an operational amplifier that will make the design of this type of oscillators with very high frequency specifications possible, available and applicable. Due to successful solutions to the limitations of the problem as explained in the sections 2 & 3 of this paper. The amount of RS (slew rate) $> 400 \text{ V}/\mu\text{s}$ for LM171AIN was used in this design as well as the output voltage Vm can be adjusted to suitable value. It turns out that RS & Vm has the most prominent role in determining the maximum output frequency (fmo) resulting from the design according to *equation (11)*.

These results beside of the unique c/s of Wien bridge can make the Wien bridge oscillator, are capable of introducing output signal with high performance characteristic for very low to very high frequency so that a Wien bridge is chosen for achieving a wider frequency range.

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